

# Modular Curves as Moduli Spaces

Math 285M Final Presentation

December 17, 2025

# Outline

- 1 Recap of Modular Curves
- 2 Modular Curves as Moduli Spaces
- 3 Some Applications

# The Modular Group and the Upper Half-Plane

- The Upper Half-Plane ( $\mathbb{H}$ ):  $\{z \in \mathbb{C} \mid \text{Im}(z) > 0\}$ . A model of hyperbolic geometry.
- The Modular Group  $SL_2(\mathbb{Z})$ :  $\begin{pmatrix} a & b \\ c & d \end{pmatrix}$  where  $a, b, c, d \in \mathbb{Z}$  and  $ad - bc = 1$ .
- Action: The group acts on  $\mathbb{H}$  by fractional linear transformations:  
$$z \mapsto \frac{az+b}{cz+d}.$$
- Fundamental Domain: A region in  $\mathbb{H}$  that contains exactly one representative from each orbit.
- Extended upper half-plane  $\mathbb{H}^* = \mathbb{H} \cup \mathbb{Q}\mathbb{P}^1$  adds a line at infinity. This will “compactify” the modular curve.

# Congruence Subgroups

- $\Gamma_0(N)$ : Matrices

$$M = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

with  $c \equiv 0 \pmod{N}$ .

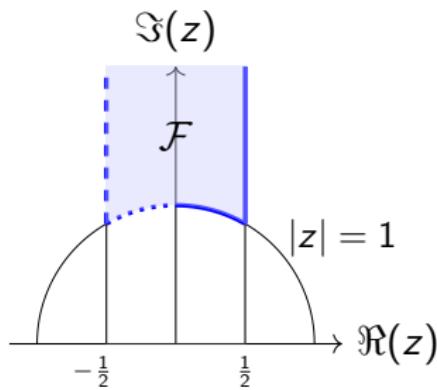
- $\Gamma_1(N)$ : Matrices with  $a, d \equiv 1 \pmod{N}$  and  $c \equiv 0 \pmod{N}$ .

# Modular Curves

We have [modular curves](#)

$$X(N) = \mathbb{H}^* / \Gamma(N), \quad X_0(N) = \mathbb{H}^* / \Gamma_0(N), \quad X_1(N) = \mathbb{H}^* / \Gamma_1(N).$$

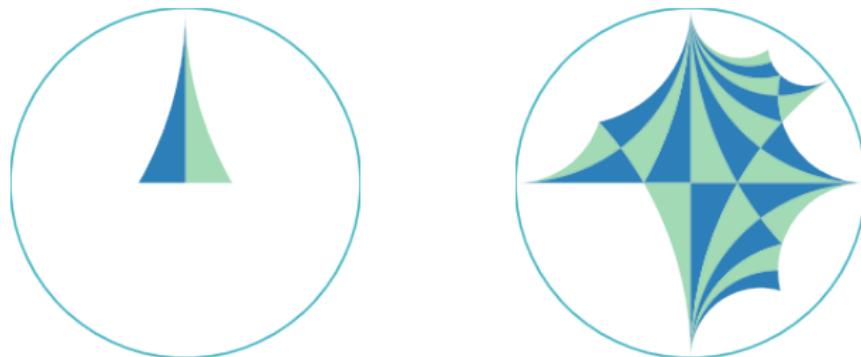
Visualize as fundamental domains.



For  $\Gamma = SL_2(\mathbb{Z})$ , the modular curve is topologically equivalent to a sphere.

# Visualizing Modular Curves

In the Poincaré disk, the fundamental domains for  $SL_2(\mathbb{Z})$  and  $\Gamma_0(11)$  are:



The modular curve  $X_0(11)$  has genus 1.

# More Fundamental Domains

(a)  $X_1(5)$ (b)  $X_1(11)$

# History of Modular Curves as Moduli Spaces

- The study of modular curves has roots in the 19th century (Gauss, Dedekind, Klein, Poincaré).
- Hecke, Siegel, and Shimura connected modular curves to the arithmetic of elliptic curves.
- The modern perspective, viewing modular curves as moduli spaces, was crystallized in Grothendieck's school in the 1960s.

# Moduli Spaces

## Definition (Rough)

A **moduli space** is a geometric space whose points represent (isomorphism classes of) algebro-geometric objects of some fixed kind.

- $\mathbb{R}_{>0}$  is a moduli space for the problem of classifying circles in  $\mathbb{R}^2$  up to congruence.
- $\mathbb{RP}^1$  is the moduli space for lines in  $\mathbb{R}^2$  passing through the origin.
- $\mathbb{RP}^2$  is the moduli space for lines in  $\mathbb{R}^3$  passing through the origin.

# Why Moduli Spaces?

Moduli Spaces  $\iff$  “solution spaces”

## Example

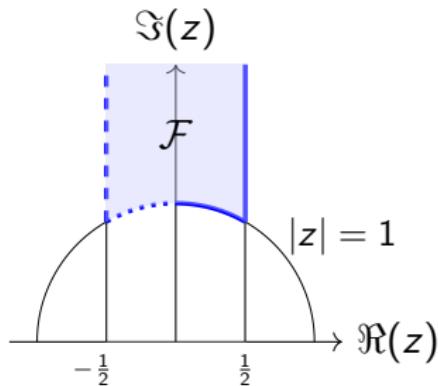
Circles in  $\mathbb{R}^2$  inherit a notion of closeness from the moduli space  $\mathbb{R}_{>0}$ .

# Modular Curves as Moduli Spaces

## Theorem (Uniformization)

Each point  $\tau \in \mathbb{H}$  gives an elliptic curve  $E_\tau \cong \mathbb{C}/\Lambda_\tau$  and this classifies all elliptic curves.

$Y(1) = \mathbb{H}/\Gamma$  is the moduli space for elliptic curves.



# Modular Curves as Moduli Spaces

We can generalize this:

- $Y_1(N) \iff (E, P)$ , where  $|P| = N$ .
- $Y_0(N) \iff (E, C)$ , where  $C \subset E$  cyclic,  $|C| = N$ .

# Proof Sketch

Let  $E$  be an elliptic curve, and  $P \in E(\mathbb{C})$  have order  $N$ .

- $E \cong \mathbb{C}/\Lambda_\tau$
- $P = (c\tau + d)/N + \Lambda_\tau$  HW!!
- Use  $\text{SL}_2(\mathbb{Z})$  to send  $\frac{c\tau + d}{N} \rightarrow \frac{1}{N}$ .
- $\Gamma_1(N)$  fixes  $\frac{1}{N} + \Lambda_\tau$ .
- Thus, consider  $\tau$  as an element of  $Y_1(N) \cong \mathbb{H}/\Gamma_1(N)$ .

# Proof Sketch

Conversely:

- Suppose  $(E_\tau, P) \cong (E_{\tau'}, P')$ , where  $E_\tau = \mathbb{C}/\Gamma_\tau$ ,  $P \cong \frac{1}{N} + \Lambda_\tau$ .
- There exists some  $\gamma \in \Gamma_1(N)$  sending  $\tau \rightarrow \tau'$ .

# Modular Curves as Riemann Surfaces

- $Y_1(N) \cong \mathbb{H}/\Gamma_1(N)$  is the moduli space for enhanced elliptic curves  $(E, P)$ , where  $P \in E(\mathbb{C})$  is a point of order  $N$ .
- $X_1(N)$  is the compactification.
- The cusps do NOT correspond to elliptic curves.

## Question

*Why do we compactify  $Y_1(N)$  to obtain  $X_1(N)$ ?*

# Modular Curves as Riemann Surfaces

## Answer

$X_*(N)$  may be described as an algebraic curve.

In fact,  $X_0(N)$  and  $X_1(N)$  can be described using polynomials with *rational* coefficients.

## Key Idea

Rational points on  $X_1(N)$  correspond to elliptic curves  $E/\mathbb{Q}$  with a point  $P \in E(\mathbb{Q})$  of order  $N$ .

# Why there are no 11-torsion points

$X_1(11)$  is parametrized by  $E_{11} : y^2 - y = x^3 - x^2$ .

- All the rational points are cusps, so NO elliptic curves over  $\mathbb{Q}$  with 11-torsion.

On the other hand,  $X_1(5)$  can be parametrized by  $x = y$ .

- Has infinitely many rational points, hence there are infinitely many elliptic curves over  $\mathbb{Q}$  with points of order 5.

# When are points of order 11 possible?

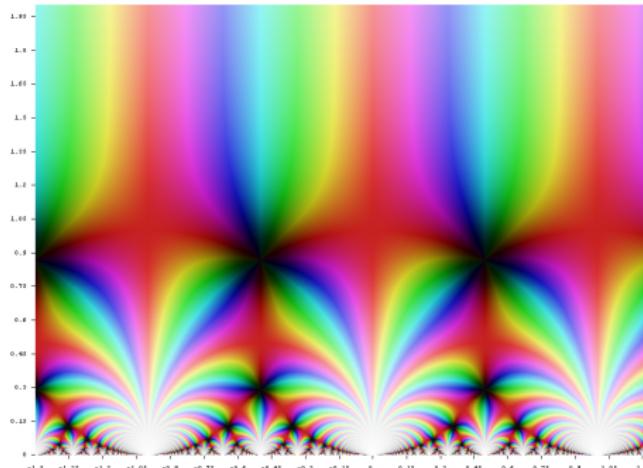
## Key Idea

More generally, points in  $K$  on  $X_1(N)$  correspond to elliptic curves  $E/K$  with points of order  $N$ .

- Let  $K = \mathbb{Q}(\sqrt{2})$ .
- Then  $P = (\frac{1}{2}, \frac{1}{4}\sqrt{2} + \frac{1}{2}) \in E_{11}(K)$
- $P$  has infinite order!
- Conclusion: infinitely many elliptic curves over  $K$  with points of order 11

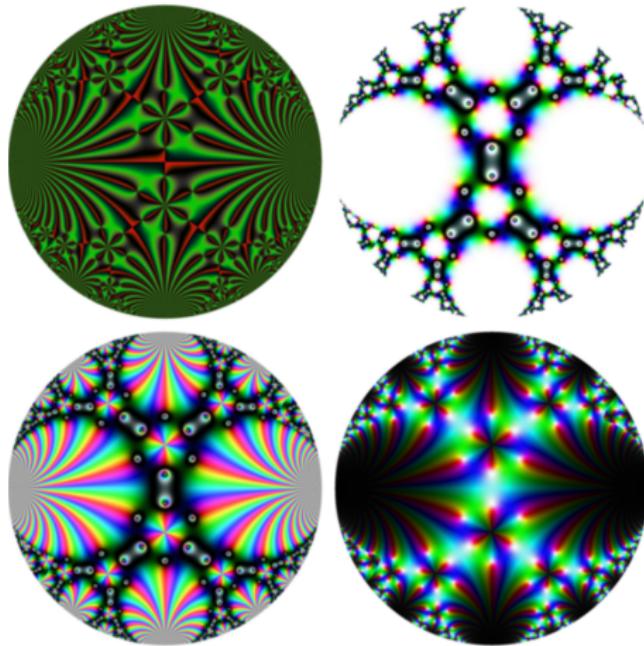
# The $j$ -invariant

For each elliptic curve  $E = E_\tau$ , we can associate a complex number  $j(\tau)$  called the  $j$ -invariant, which uniquely determines  $E$  up to isomorphism. The function  $j(\tau)$  is a modular function!



# The $j$ -invariant

In the Poincaré disk, it looks like:



# What does $X_0(11)$ look like?

The functions  $j(11\tau)$  and  $j(\tau)$  generate  $\mathcal{M}(\Gamma_0(11))$ .

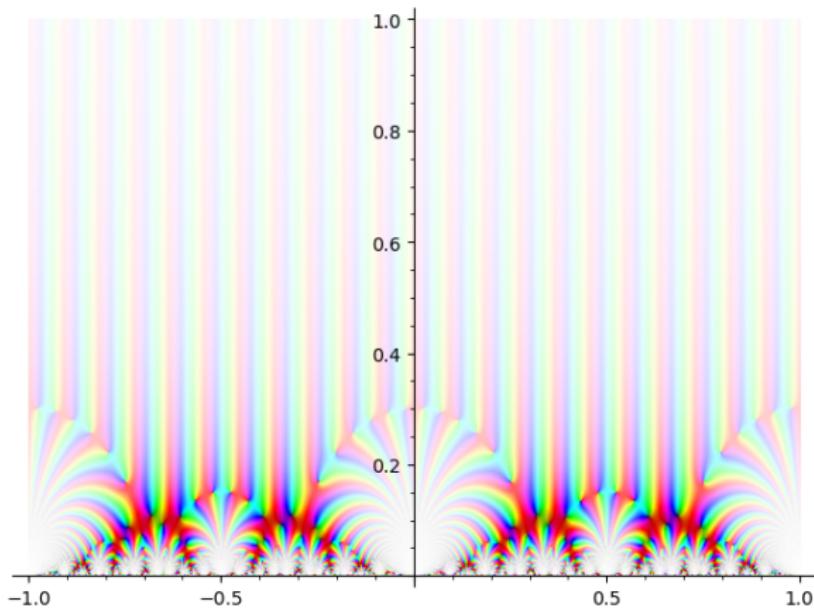
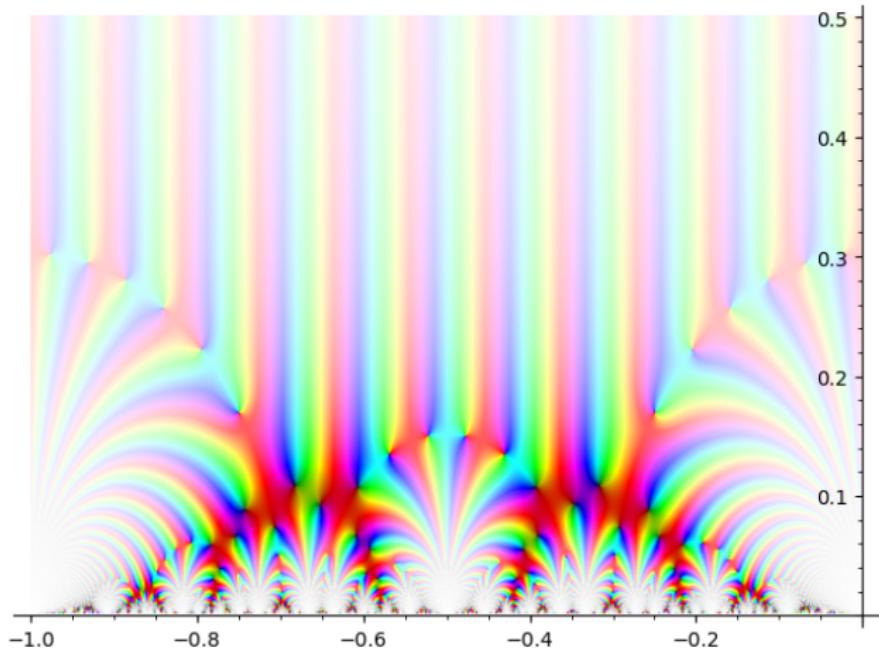


Figure: The modular form  $(j(11\tau) + j(\tau))/1728$

Another view of  $X_0(11)$ Figure: The modular form  $(j(11\tau) + j(\tau))/1728$

# References

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